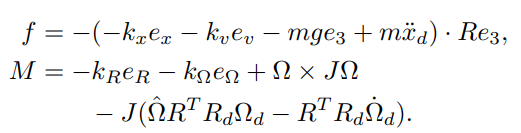
HW9 deadline: 2020/05/12

Please find the attached for the Simulink model for the UAV.

The homework is to **design a geometric controller** to track a desired attitude.

e.g.,

1. You need to modify “**controller.m**”
2. There is explanation for every function in “**readme.txt**”
3. Don’t implement this term.